

# Lattice Walks Restricted to the Positive Quarter Plane (and Octant)

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and Marni Mishna



## Lattice Walks in the Quarter Plane

**Given:** A set of directions

**Count:** Number of integer lattice walks in the first quadrant using these steps.

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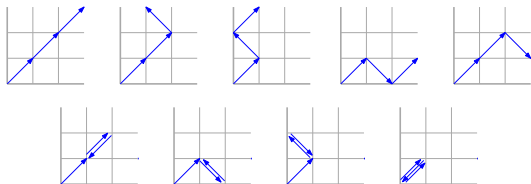
**Given:** A set of directions

**Count:** Number of integer lattice walks in the first quadrant using these steps.

For instance, given the step set  $S = \{NE, SE, NW, SW\}$



there are 9 walks of length 3:






## Realistic Goals

Finding a formula to predict the number of walks of length  $n$  is too hard in general - we seek **asymptotic estimates**.

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If we can classify the generating function as algebraic or D-Finite (satisfies a nice linear ODE) then we will know the form of its growth.

Classification	Growth	Example
Algebraic	$\frac{c\beta^n n^s}{\Gamma(s+1)}$	
D-Finite	$A\beta^n n^s \log(n)^r$	
Neither	--	

# Outline of this Talk

Classifying the Generating Function

Proofs via the 'Kernel Method'

Asymptotics of D-Finite Walks

Automatic Guessing of Bostan and Kauers

Extension to 3D

Reductions to previous cases

Orbit sum methods

## Classifying the Generating Function

## History

Of  $2^8 = 256$  step sets, we consider only 79 [B.M.&Mishna 2010].  
Step sets which are subsets of



correspond to half space problems, which have been previously solved [Banderier&Flajolet 2001].



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Step sets which are subsets of



correspond to half space problems, which have been previously solved [Banderier&Flajolet 2001].

Also, subsets of



will never leave the origin, so these are also not considered.

## Tools

The generating function

$$Q(x, y; t) = \sum_{n, i, j \geq 0} q(i, j; n) x^i y^j t^n$$

which counts the number of walks of length  $n$  ending at  $(i, j)$  satisfies an obvious functional equation.

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which counts the number of walks of length  $n$  ending at  $(i, j)$  satisfies an obvious functional equation. For example, with the previous step set

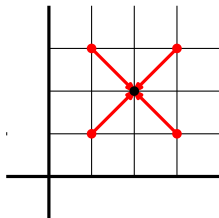


we define the step generating function

$$S(x, y) := xy + \frac{y}{x} + \frac{1}{xy} + \frac{x}{y}$$

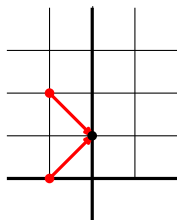
## A functional equation

$$Q(x, y; t) = 1 + tS(x, y)Q(x, y; t)$$



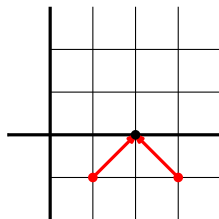
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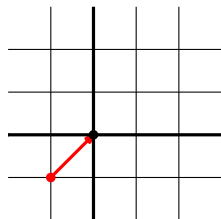
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## The Kernel Equation

Begin with the functional equation, re-group the terms and multiply by  $xy$  to give:

$$K(x,y) \cdot xyQ(x,y) = xy - t(y^2+1)Q(y,0) - t(x^2+1)Q(x,0) + tQ(0,0) \quad (K)$$

where  $K(x, y) = 1 - tS(x, y)$  is called the *kernel* of the walk.



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We now define a group  $G$  of bi-rational transformations of the  $xy$ -plane which preserves  $S(x, y)$  - and thus  $K(x, y)$ .

## The Group of a Walk

To begin, write

$$S(x, y) = \frac{1}{y}A_{-1}(x) + A_0(x) + yA_1(x) = \frac{1}{x}B_{-1}(y) + B_0(y) + xB_1(y).$$

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We let  $G$  be the group generated by the involutions

$$\psi : (x, y) \mapsto \left( \frac{B_{-1}(y)}{xB_1(y)}, y \right) \quad \tau : (x, y) \mapsto \left( x, \frac{A_{-1}(x)}{yA_1(x)} \right).$$

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In our case, we have

$$\psi : (x, y) \mapsto \left( \frac{1}{x}, y \right) \quad \tau : (x, y) \mapsto \left( x, \frac{1}{y} \right),$$

so  $G$  contains 4 elements:  $id, \psi, \tau\psi, \psi\tau\psi$ .

## Summing the Kernel Equation

Applying the group elements to  $(K)$  yields:

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If we take an **alternating sum** of these equalities, all **unknown terms on the RHS cancel!**

## Proving D-Finiteness

In 19 of the 23 cases where the group of a walk is finite, we get:

Theorem (Bousquet-Mélou&Mishna 2010)

$$\sum_{g \in G} \text{sign}(g)g(xy)Q(g(x, y)) = \frac{1}{K(x, y)} \sum_{g \in G} \text{sign}(g)g(xy),$$

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Three of the other four walks use a modified ‘half-orbit sum’ method, the last (Gessel’s walk) is special.

# Automatic Asymptotics

## How it Works

We calculate lots of terms, then guess a differential equation with certain bounds (implemented in gfun, others).

Given a step set  $\mathcal{S}$ , we can use a recursive formula to find  $q(i, j; n)$  starting with  $q(0, 0; 0) = 1$ .

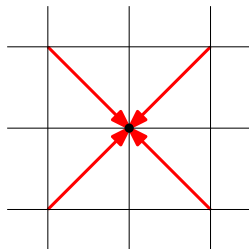
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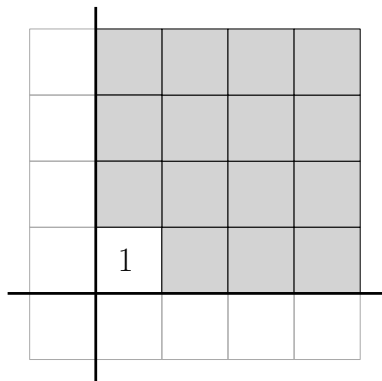
For example, if  $\mathcal{S} = \begin{array}{c} \nearrow \\ \searrow \end{array}$  then

$$\begin{aligned} q(i, j; n) = & q(i - 1, j - 1; n - 1) \\ & + q(i - 1, j + 1; n - 1) \\ & + q(i + 1, j - 1; n - 1) \\ & + q(i + 1, j + 1; n - 1) \end{aligned}$$

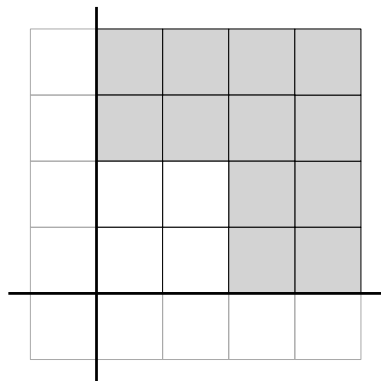


[we only add terms with positive arguments]

## Illustration of the Algorithm



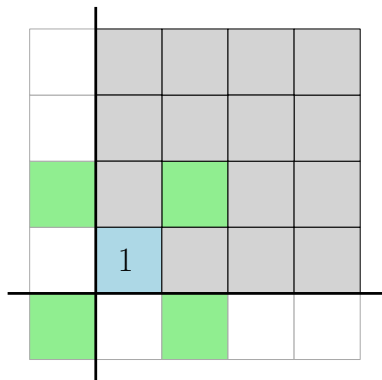
$n = 0$



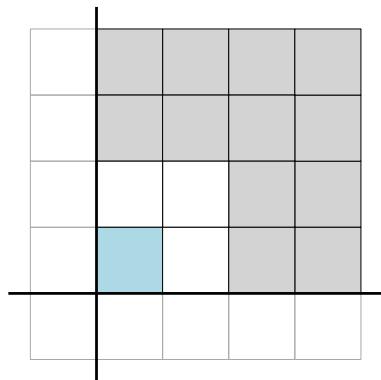
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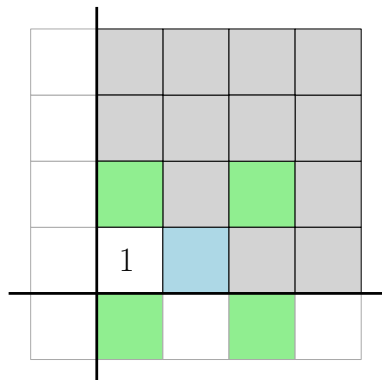


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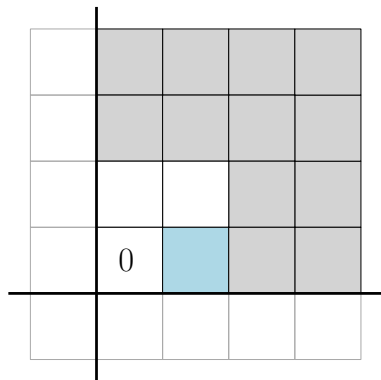


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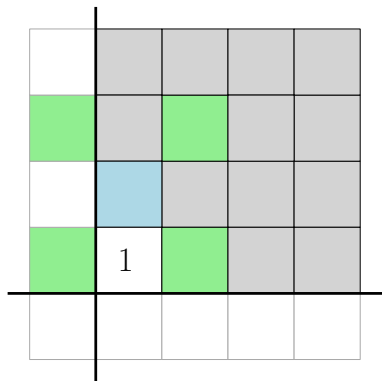


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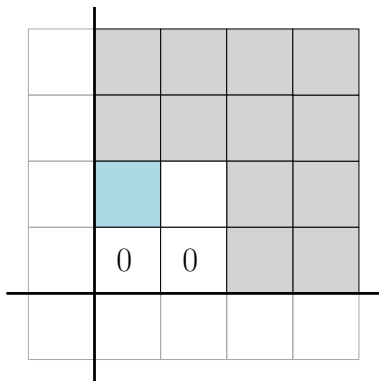


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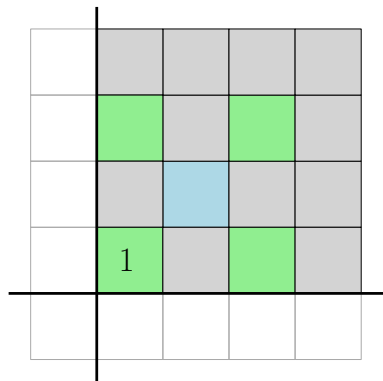


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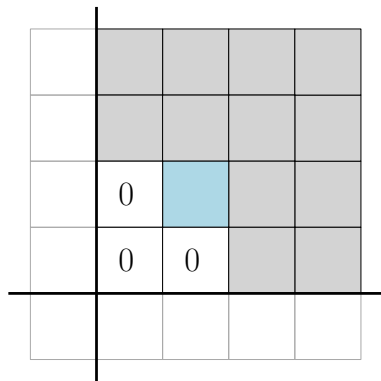


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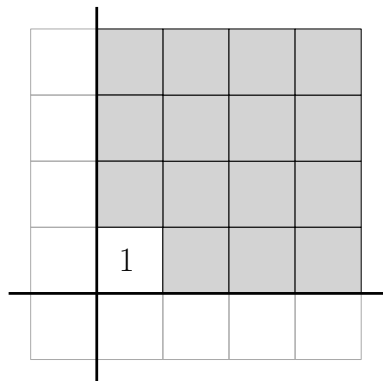


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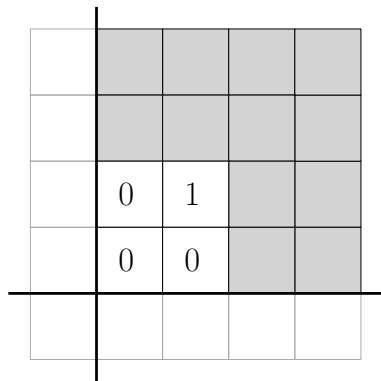


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







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## Calculating Lots of Terms in C

Algorithm	Time (Modular)	Space (Modular)	Time (Naive)	Space (Naive)
500 Steps 	36 s	4 MB	10 s	48 MB
1000 Steps 	671 s	17 MB	123 s	270 MB
3000 Steps 	59509 s	142 MB	7576 s	5294 MB
500 Steps 	59 s	4 MB	59 s	50 MB
1000 Steps 	1029 s	17 MB	135 s	282 MB
3000 Steps 	89600 s	144 MB	8515 s	5635 MB

We can calculate a sufficient number of terms to guess quickly.



## Selected step sets and their asymptotic behaviour






$S$	$c$	$s$	$\beta$	Asymptotic Form
	$\frac{2}{\pi}$	-1	4	$\frac{2}{\pi} \cdot \frac{4^n}{n}$
	$\sqrt{\frac{3}{\pi}}$	$-\frac{1}{2}$	3	$\sqrt{\frac{3}{\pi}} \cdot \frac{3^n}{\sqrt{n}}$
	$\frac{\sqrt{5}}{2\sqrt{2}\pi}$	$-\frac{1}{2}$	5	$\frac{\sqrt{5}}{2\sqrt{2}\pi} \cdot \frac{5^n}{\sqrt{n}}$
	$\frac{24\sqrt{2}}{\pi}$	-2	$2\sqrt{2}$	$\frac{24\sqrt{2}}{\pi} \cdot \frac{(2\sqrt{2})^n}{n^2}$
	$\frac{\sqrt{8}(1+\sqrt{2})^{\frac{7}{2}}}{\pi}$	-2	$2(1+\sqrt{2})$	$\frac{\sqrt{8}(1+\sqrt{2})^{\frac{7}{2}}}{\pi} \cdot \frac{(2(1+\sqrt{2}))^n}{n^2}$

Table: Some results of [Bostan&Kauers 2009].

## 3D Walks

## Basic Idea

Now, we look at walks in the  $xyz$ -plane restricted to the positive octant.



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We focus on the 83,682 with 5 steps or less. Bostan and Kauers conjectured (up to equivalence) 35 D-Finite steps.

## Orbit Sums

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There are 8 sets with an *infinite group*.



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If  $(x)$  is satisfied then  $(y)$  must be satisfied!

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Thus, if

$$R(s, t, u, v, w) = \sum_{a, b, c, d, e \geq 0} r(a, b, c, d, e) s^a t^b u^c v^d w^e$$

$$R'(s, t, u) = \sum_{A, B, C \geq 0} r(A, B, C) s^A t^B u^C$$

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are the generating functions of these walks marked by the number of each step, we have

$$R(s, t, u, v, w) = R'(s, t, u + v + w).$$



## Reduction to 2D

Furthermore,  $R$  and  $R'$  are algebraic substitutions of  $Q(x, y, z; t)$  and  $Q'(x, y; t)$ :

$$Q(x, y, z; t) = R \left( \frac{t}{z}, txy, \frac{tyz}{x}, \frac{tz}{x}, \frac{tz}{xy} \right)$$
$$Q'(x, y; t) = R' \left( \frac{t}{x}, ty, \frac{t}{xy} \right)$$

## Reduction to 2D

Furthermore,  $R$  and  $R'$  are algebraic substitutions of  $Q(x, y, z; t)$  and  $Q'(x, y; t)$ :

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Thus, we get  $Q(x, y, z; t) = Q'(X, Y; T)$  where

$$T = t(1 + y + y^2)^{1/3} \quad X = \frac{zT}{t} \quad Y = \frac{xyt}{T}.$$

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$Q'(x, 1/x; t)$  is known to be algebraic [B.M.&Mishna 2010], thus so is  $Q\left(x, y, \frac{1}{xy}; t\right)$  for all  $x, y, t$ .

Conclusion

# Results

2D walks (almost) completely classified

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Keep pushing for larger step sets (more dimensions?)

Develop filters in 3D to apply before guessing



## References

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THANK YOU