

Population protocols & Ehrenfest urns scheme

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2008/12/01

Population protocols : the example of the majority

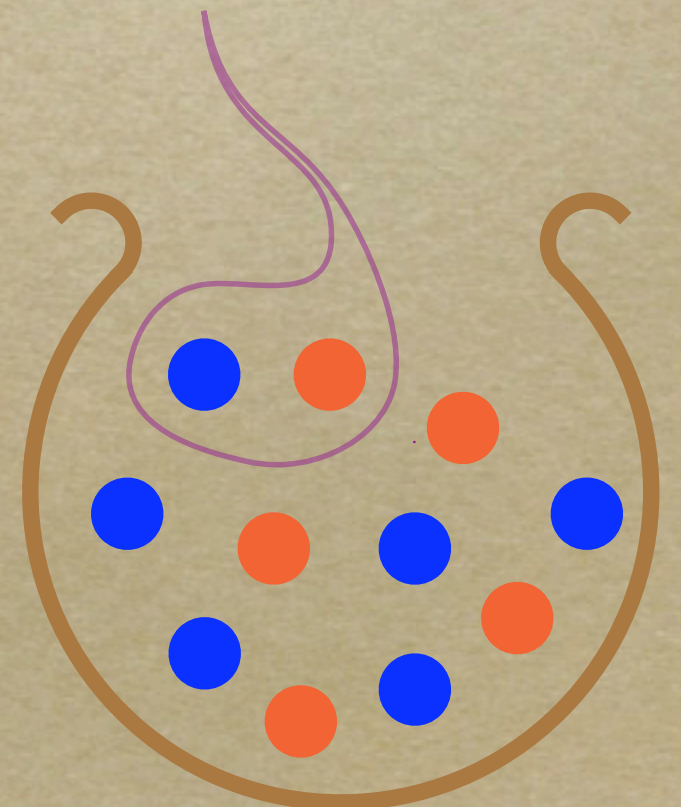
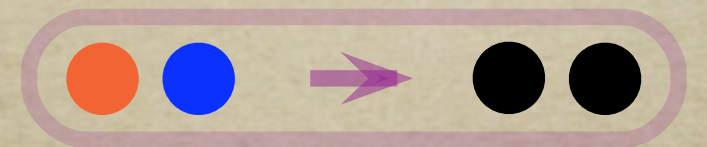
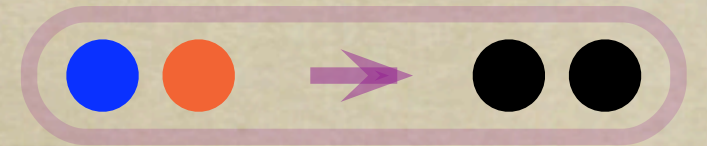
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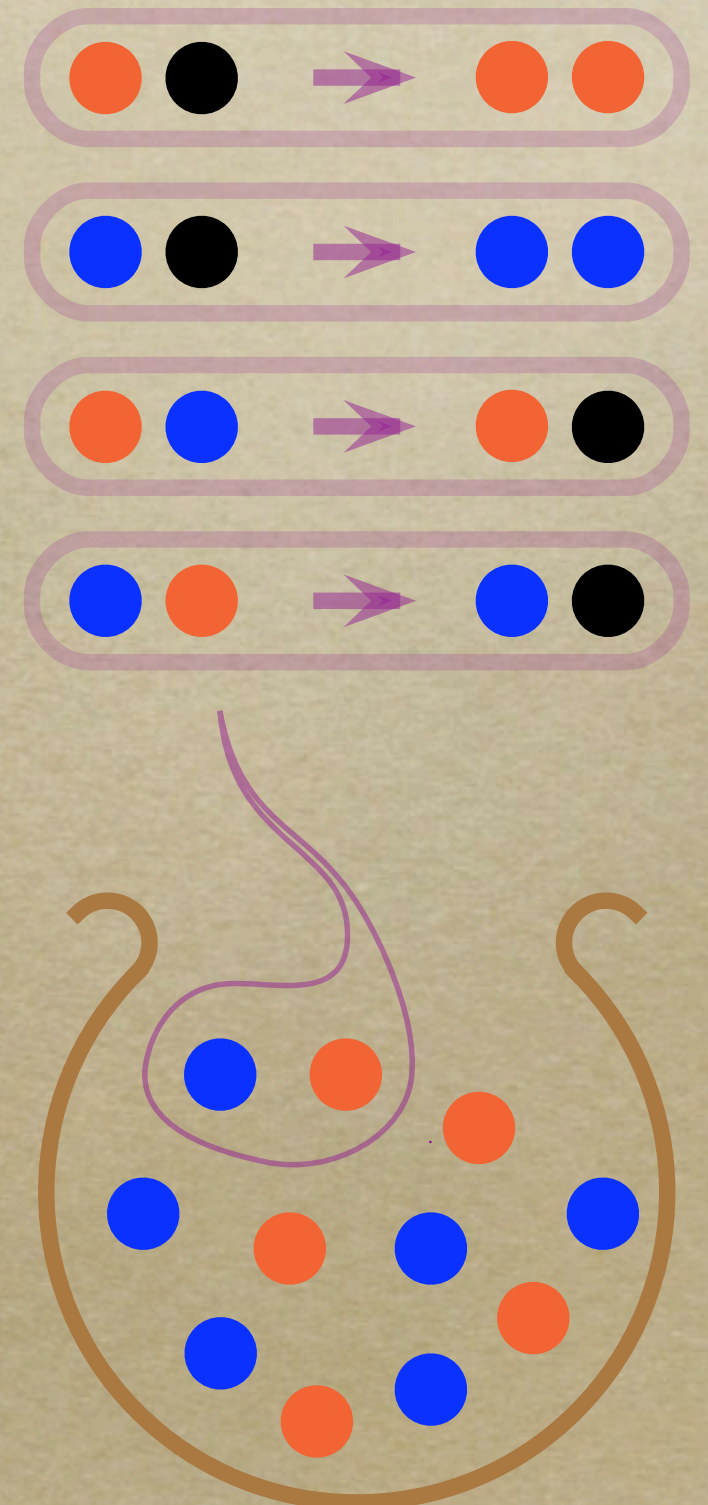
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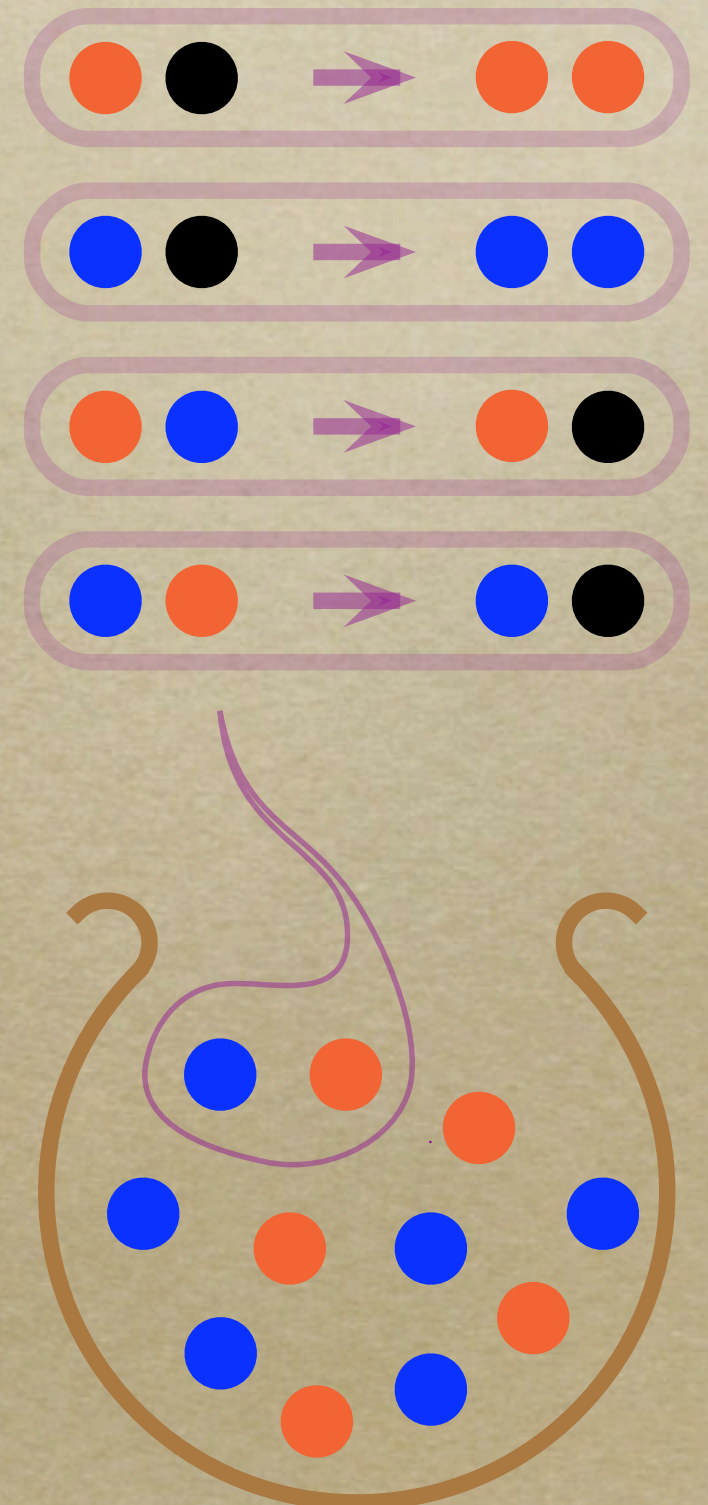
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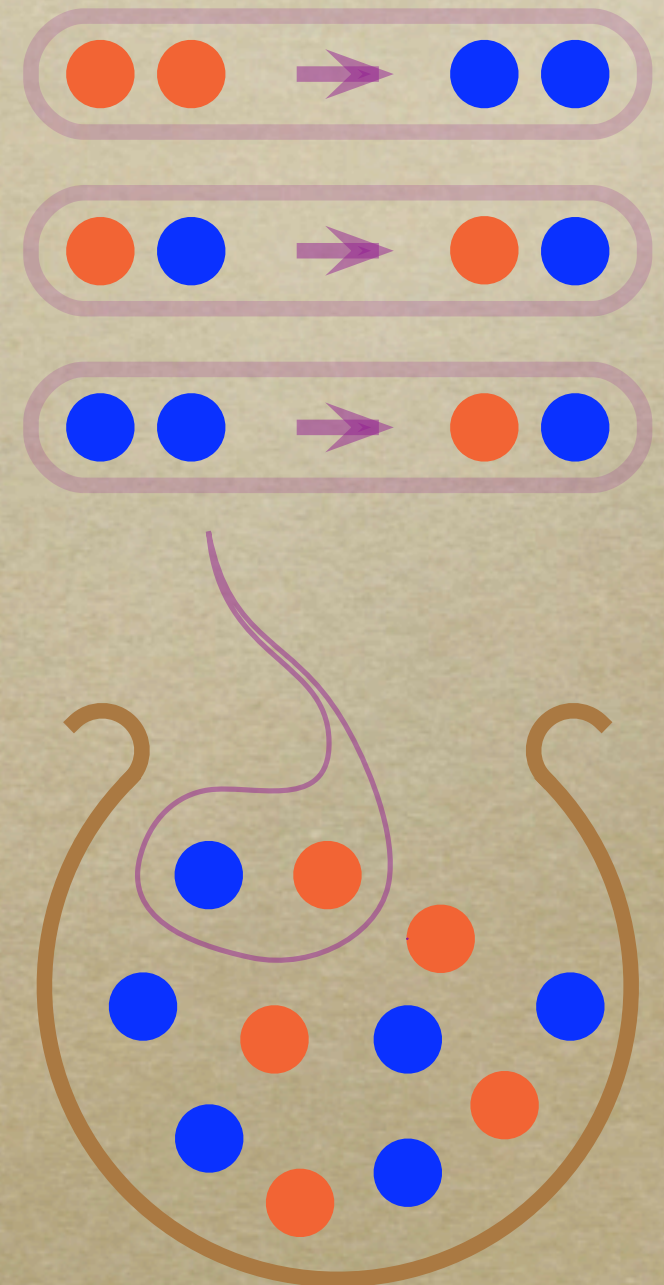
Population protocols : the example of the majority

- *Aim.* Initially, to compute predicates.
- *Example.* The majority problem: is “there is a majority of blue balls” true or false ?
- *Theorem* (Angluin et al., 2007). A predicate is computable in the basic population protocol model if and only if it is semilinear.



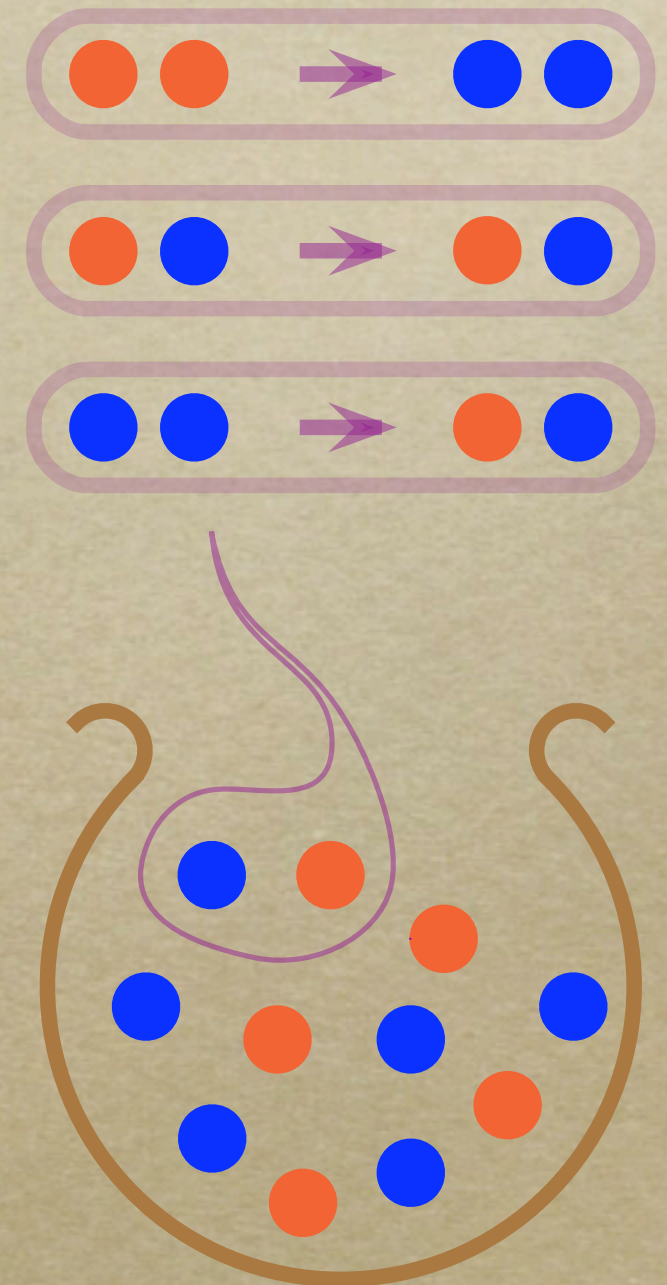
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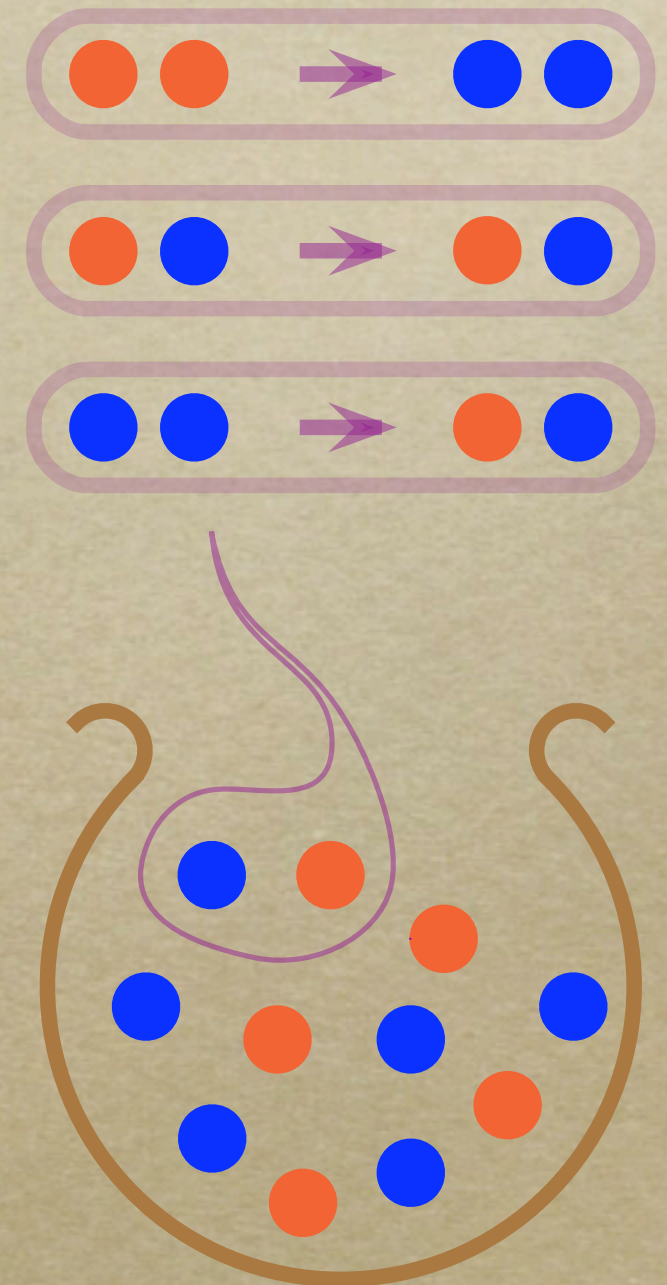
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- *Example.* The protocol pictured on the right computes $p=2-\sqrt{2}=0.58\dots$. More precisely,



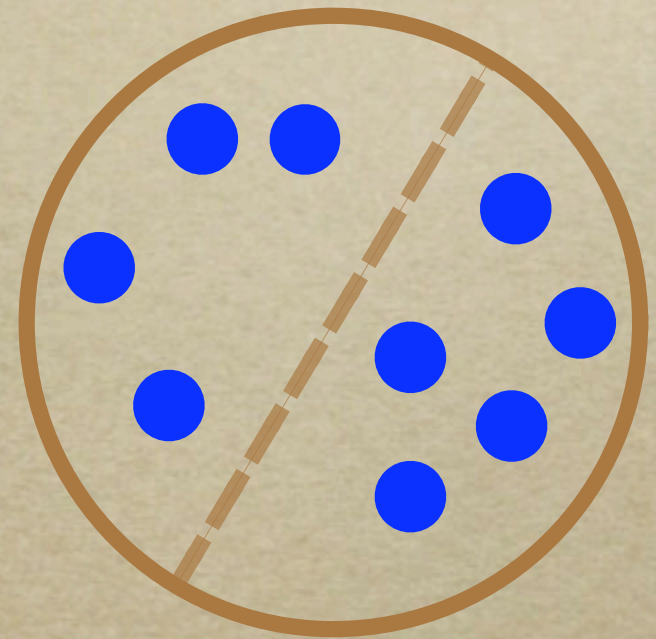
Population protocols : a variant

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- **Example.** The protocol pictured on the right computes $p=2-\sqrt{2}=0.58\dots$. More precisely,
- **Theorem** (Ph. Ch., Bournez et al.). The stationary distribution of the proportion of *blue* balls converges to p , when the number N of balls goes to ∞ . The error term is $O(N^{-1/2})$.



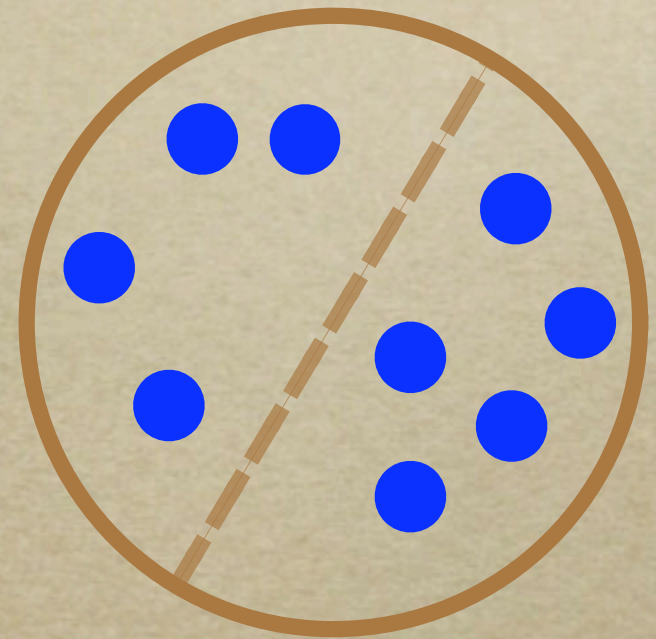
Ehrenfest: the two-chambers urn

- An urn contains N (here $N=9$) balls in its 2 chambers.
- Pick a ball at random and move it from its chamber to the other chamber, and repeat.



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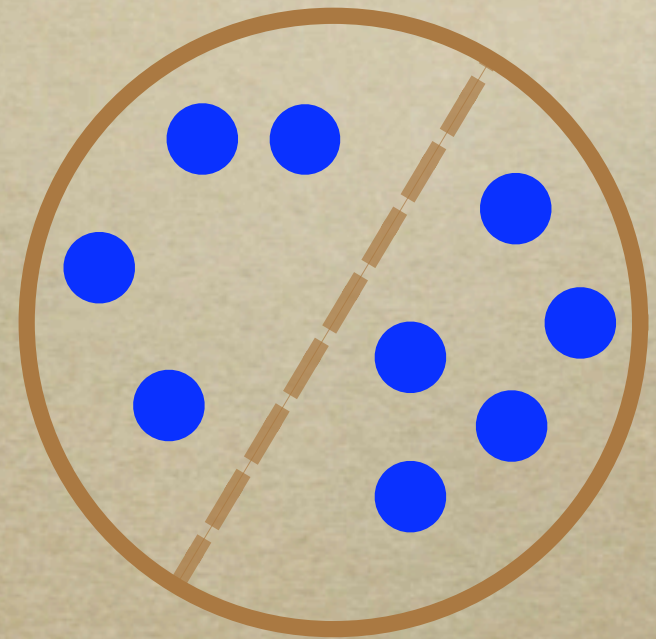
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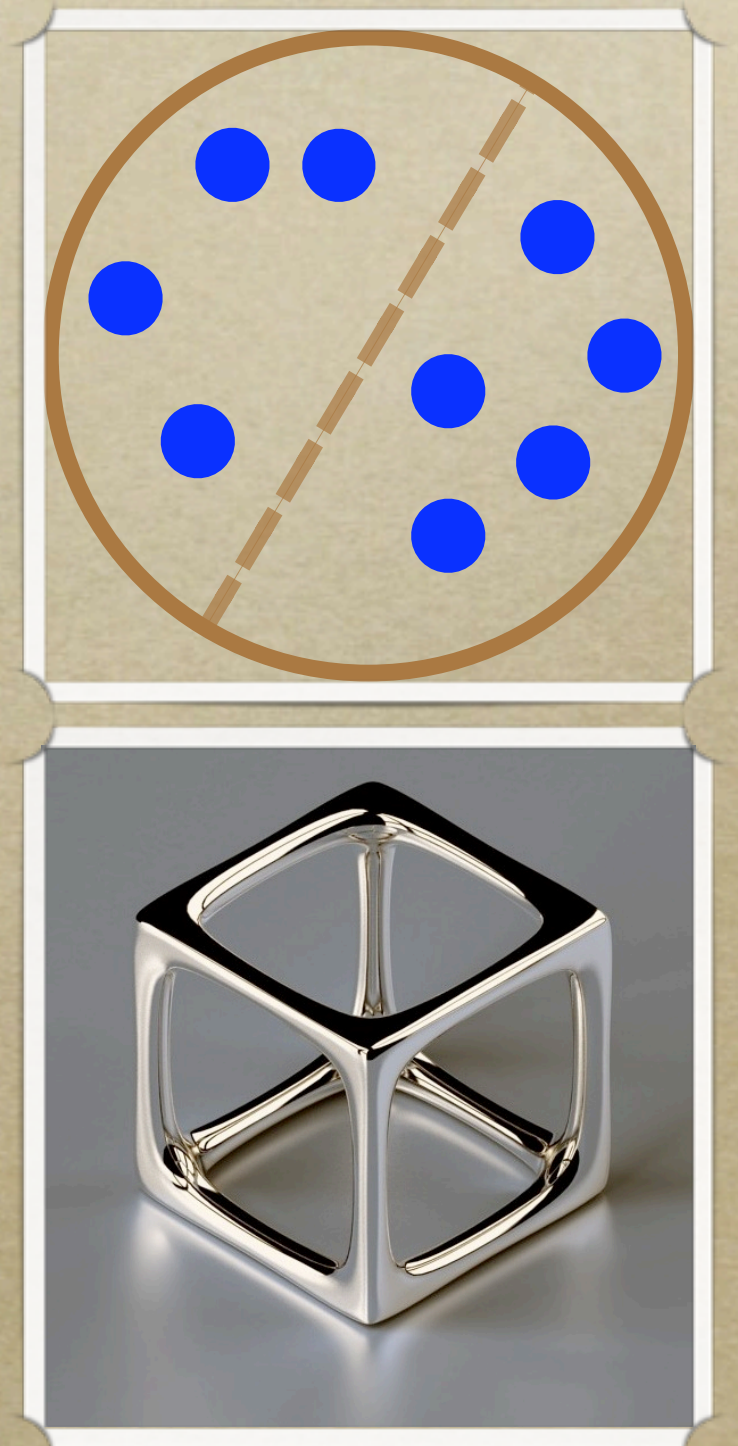
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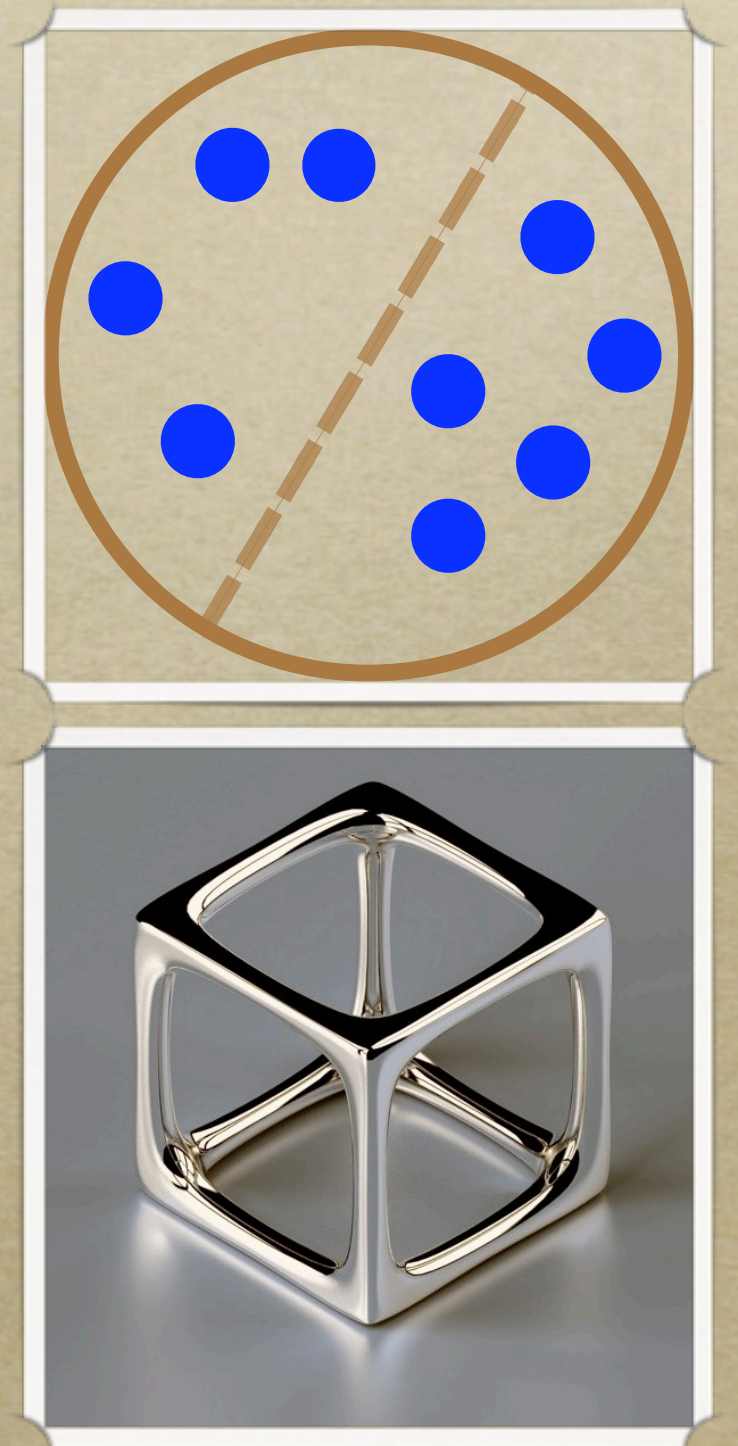


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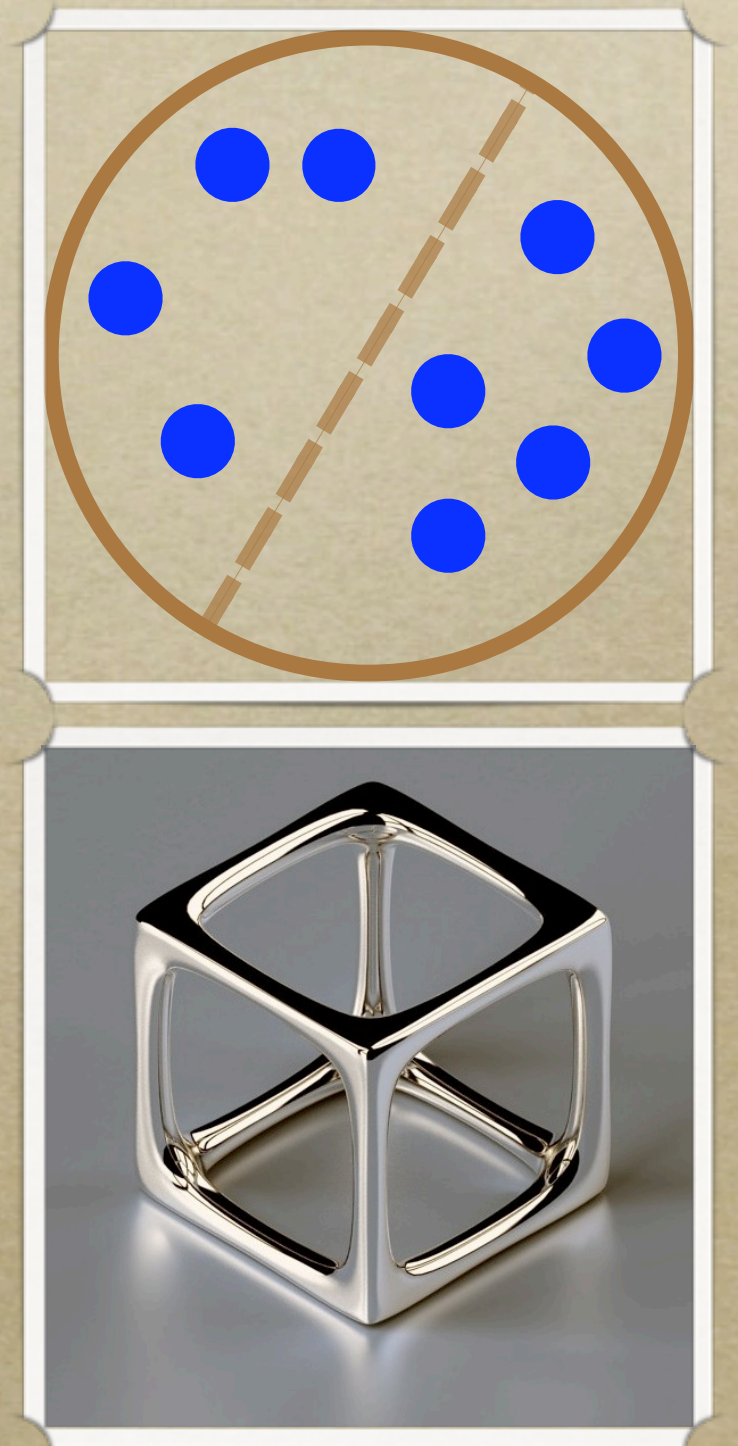
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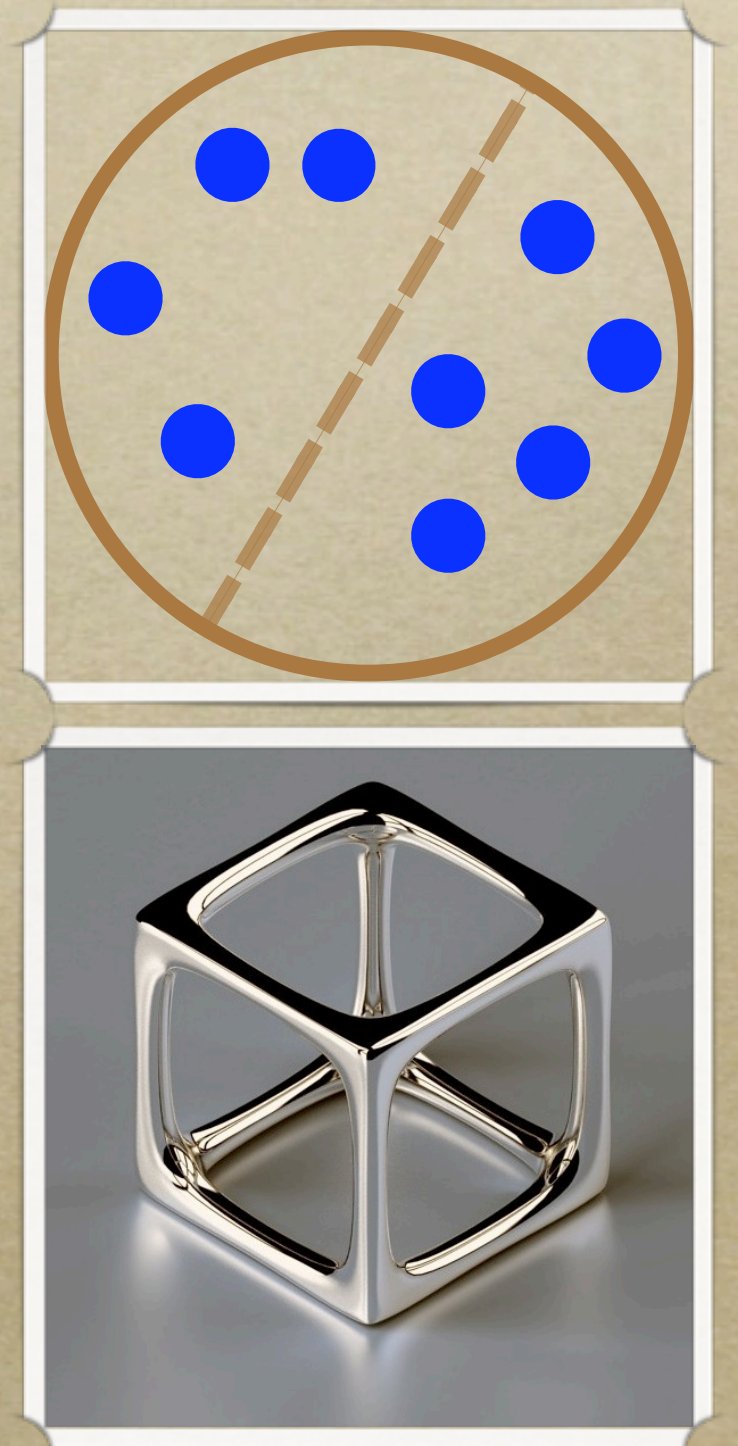


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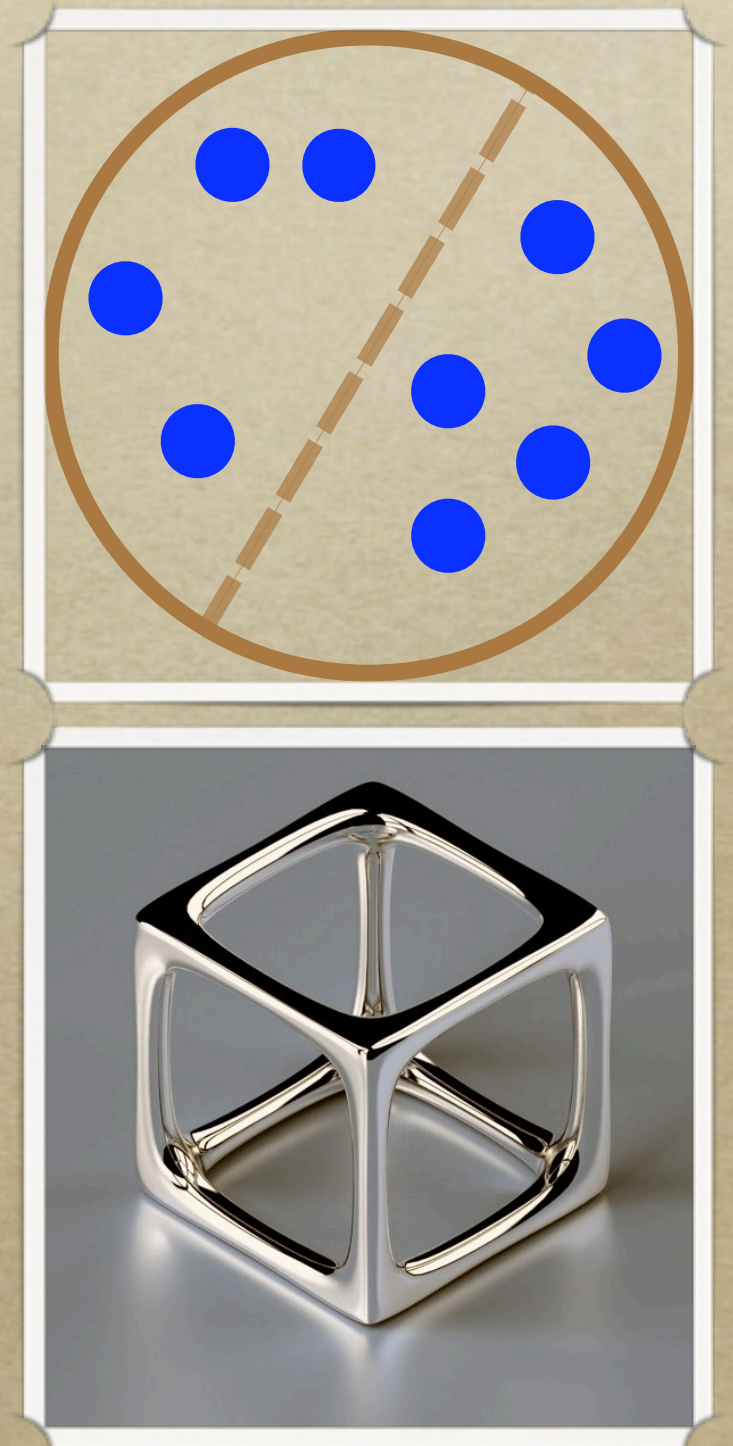
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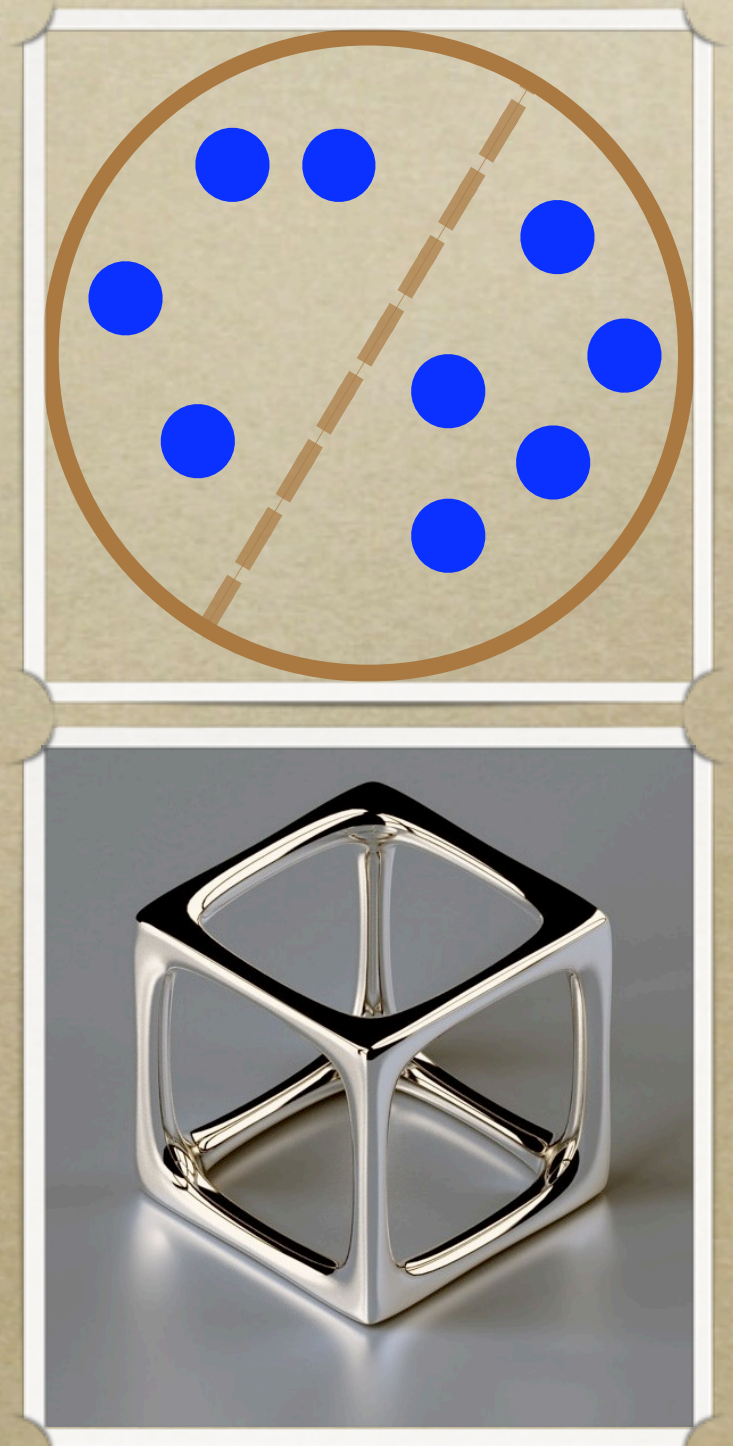
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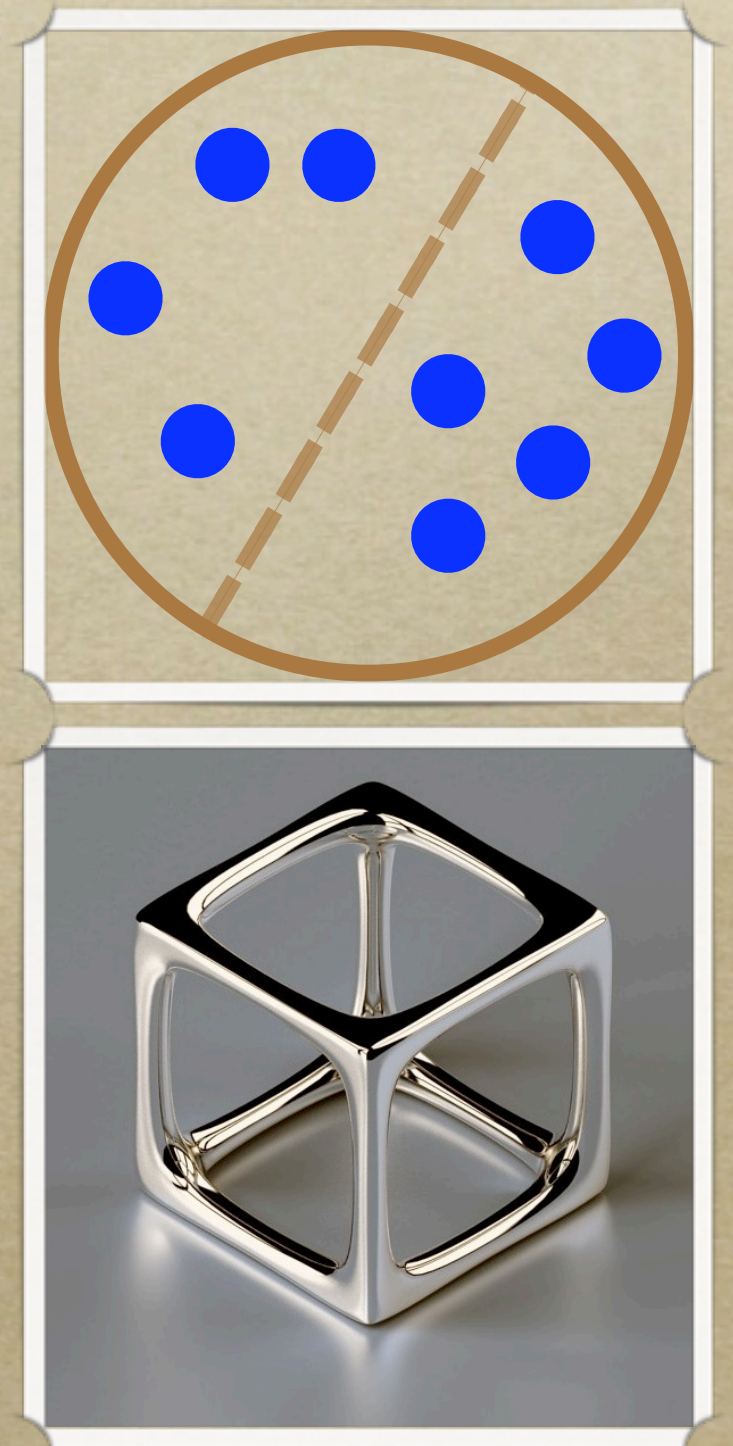
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Thus the binomial distribution $(N, 0.5)$ is stationary for the Markov chain X .



Balanced urn models

Urn evolution rule. A ball is chosen from the urn, with all balls present in the urn at that time having equal chances of being chosen, and its colour is inspected. If the ball chosen is *orange*, then α new *orange* balls and β new *blue* balls are placed into the urn; if the ball chosen is *blue*, then γ new *orange* balls and δ new *blue* balls are placed into the urn.

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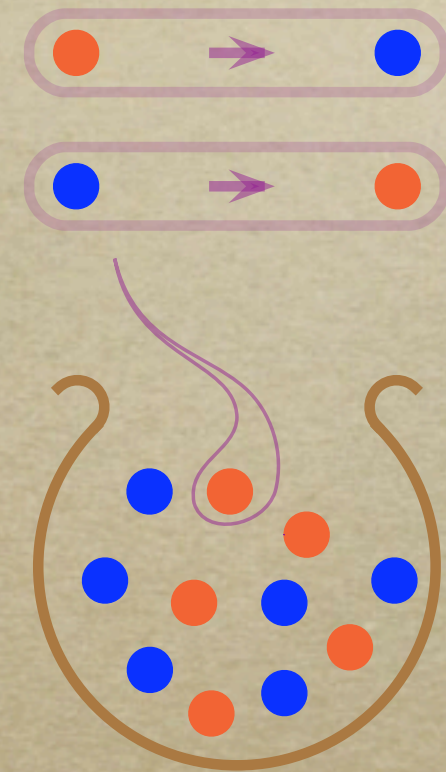
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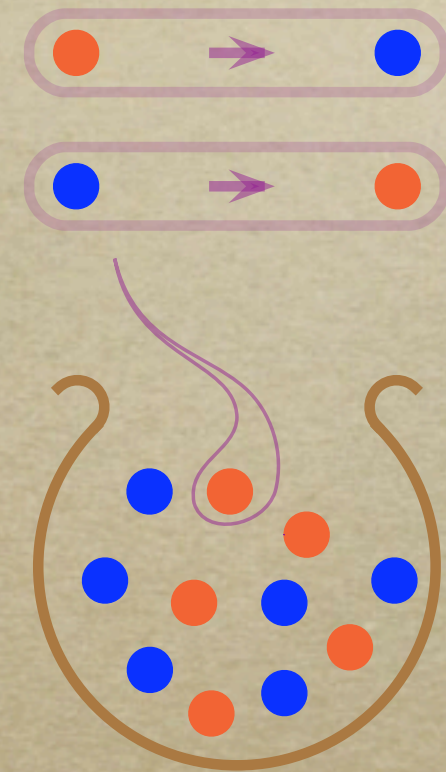
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$$\begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} = \begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix}$$

The associated differential system

*Theorem (Flajolet et al., 2006). For a **balanced** urn model, the generating function of histories starting from state (a_0, b_0) and ending at (a, b) after n steps,*

$$H \left(x, y, z \left| \begin{smallmatrix} a_0 \\ b_0 \end{smallmatrix} \right. \right) = \sum_{n, a, b} H_n \left(\begin{smallmatrix} a_0 & a \\ b_0 & b \end{smallmatrix} \right) x^a y^b \frac{z^n}{n!},$$

is given by

$$H(x_0, y_0, z) = X \left(z \left| \begin{smallmatrix} x_0 \\ y_0 \end{smallmatrix} \right. \right)^{a_0} Y \left(z \left| \begin{smallmatrix} x_0 \\ y_0 \end{smallmatrix} \right. \right)^{b_0},$$

in which X and Y are solutions of

$$\Sigma : \begin{cases} \dot{x} = x^{\alpha+1} & y^{\beta} \\ \dot{y} = x^{\gamma} & y^{\delta+1} \end{cases}$$

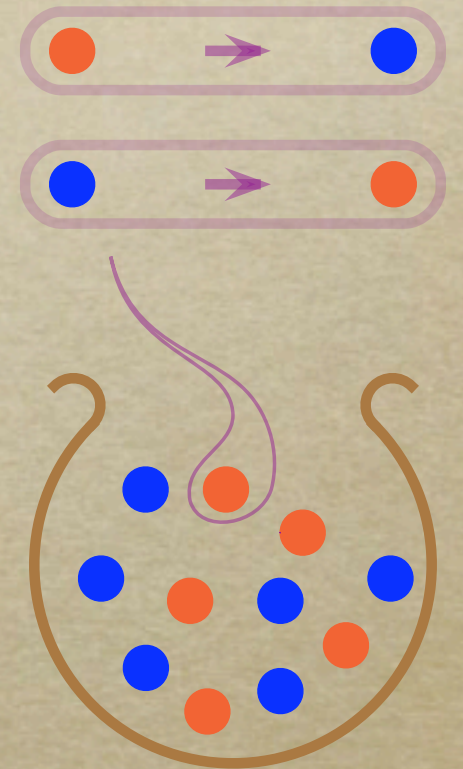
with initial conditions (x_0, y_0) .

The associated differential system : the case of the Ehrenfest model

For the Ehrenfest model, the associated differential system is quite simple:

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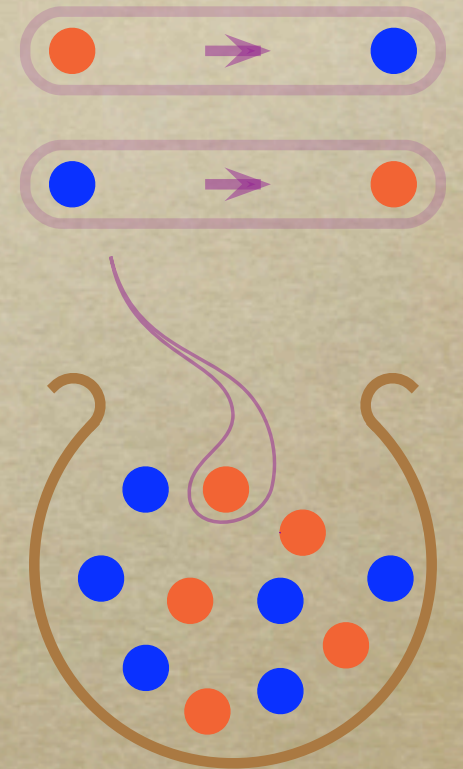
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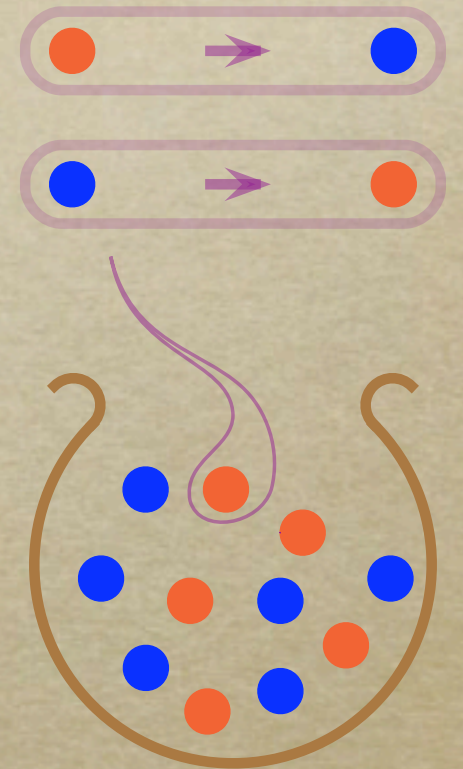
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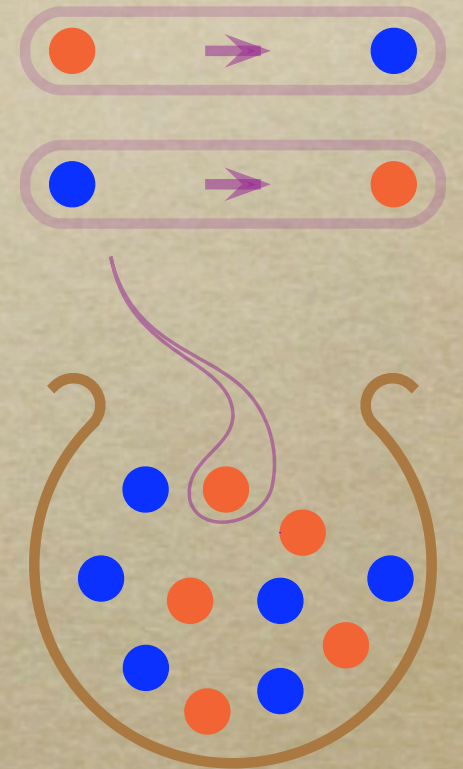
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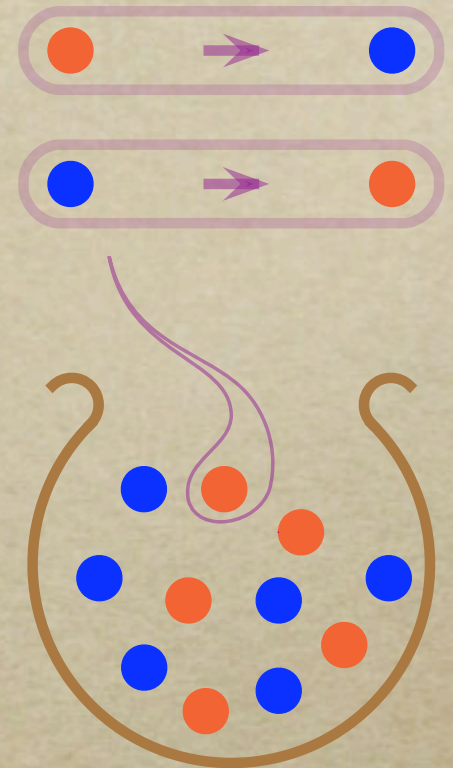
$$p_{N,0}^{(n)} = \frac{n!}{N^n} [z^n] \cosh^N z = \frac{1}{N^n 2^N} \sum_{k=0}^N \binom{N}{k} (N-2k)^n.$$



The rescaled Markov chain

Set:

$$Y_t = \frac{2X_{\lfloor Nt \rfloor} - N}{2\sqrt{N}}, \quad \Delta Y_t = Y_{t+\frac{1}{N}} - Y_t.$$

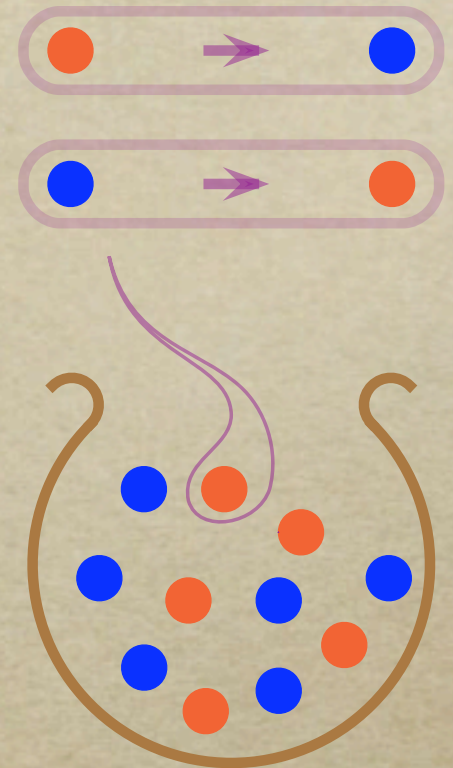


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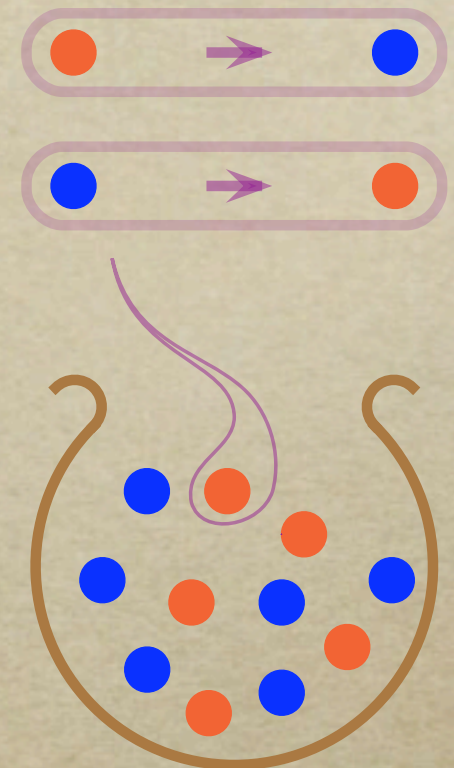
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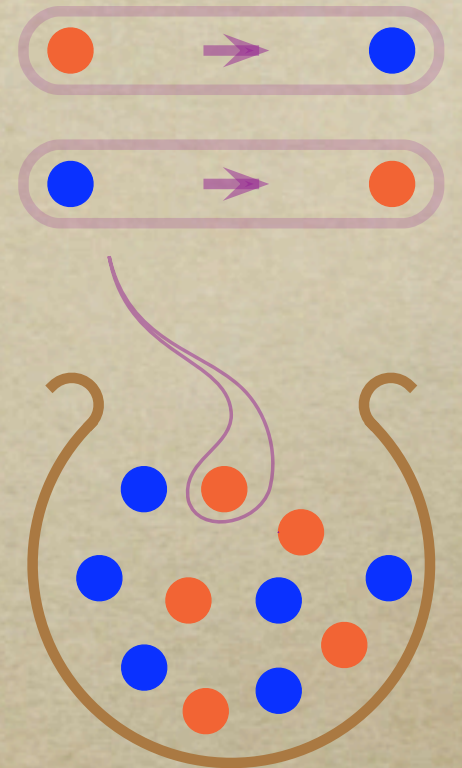
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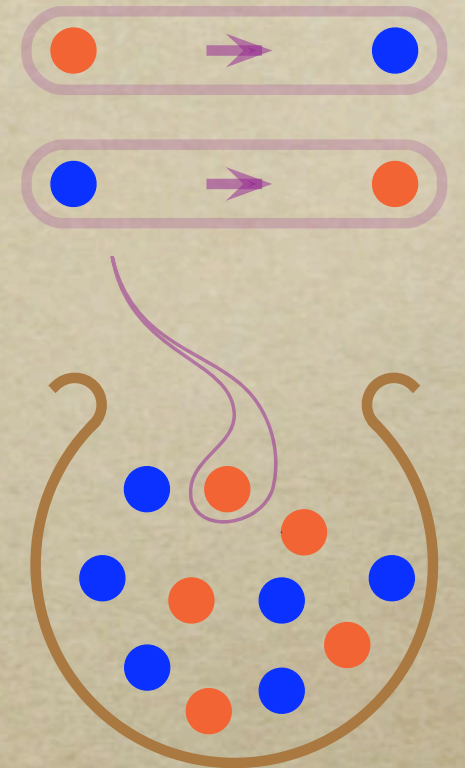
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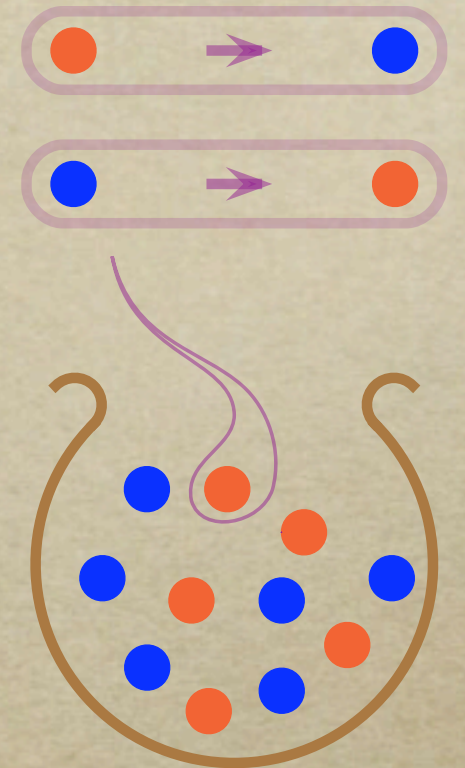
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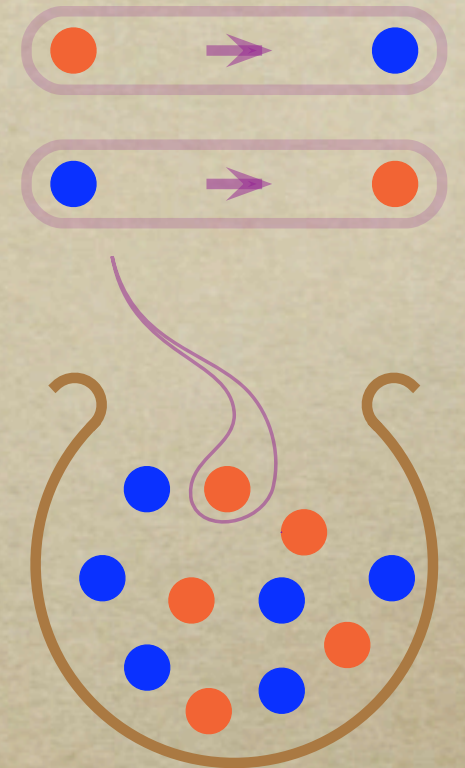
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The Ornstein-Uhlenbeck process

Any solution Y_t of the SDE:

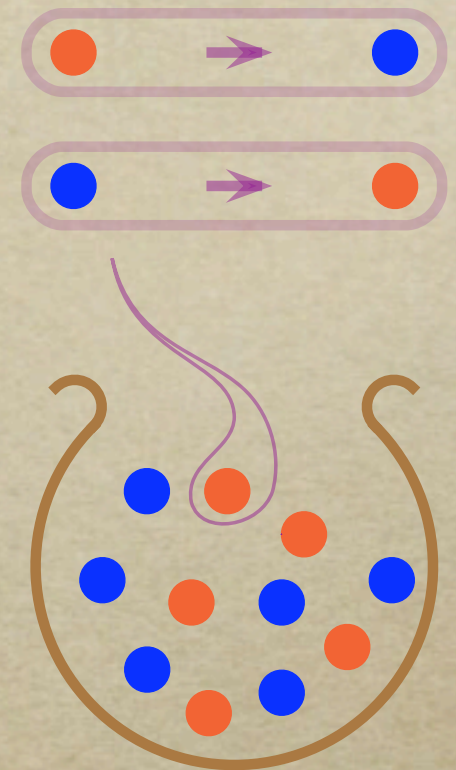
$$dY_t = -\theta(Y_t - \mu) dt + \sigma dB_t.$$

is an Ornstein-Uhlenbeck process. It admits a Gaussian stationary distribution. The stationary variance is given by:

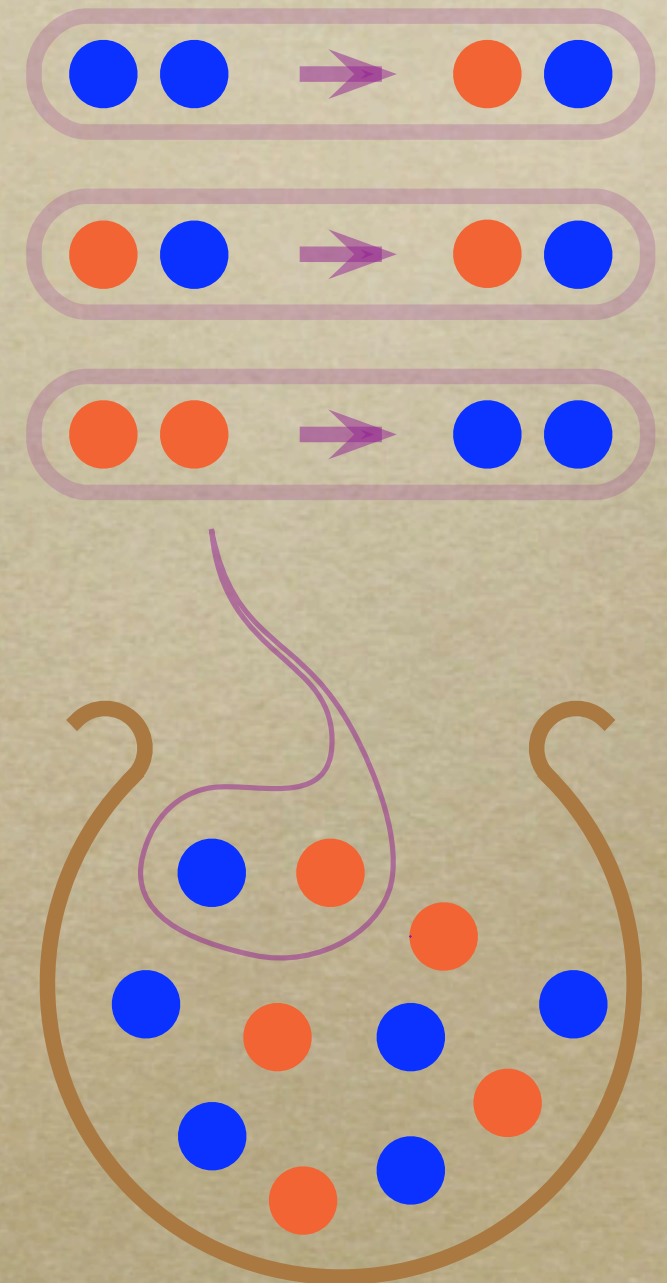
$$\text{Var}(Y_\infty) = \frac{\sigma^2}{2\theta}.$$

An Ornstein-Uhlenbeck process Y_t has closed-form representation in terms of the *Brownian motion* $B(t)$:

$$Y_t = Y_0 e^{-\theta t} + \mu(1 - e^{-\theta t}) + \frac{\sigma}{\sqrt{2\theta}} B(e^{2\theta t} - 1) e^{-\theta t}.$$

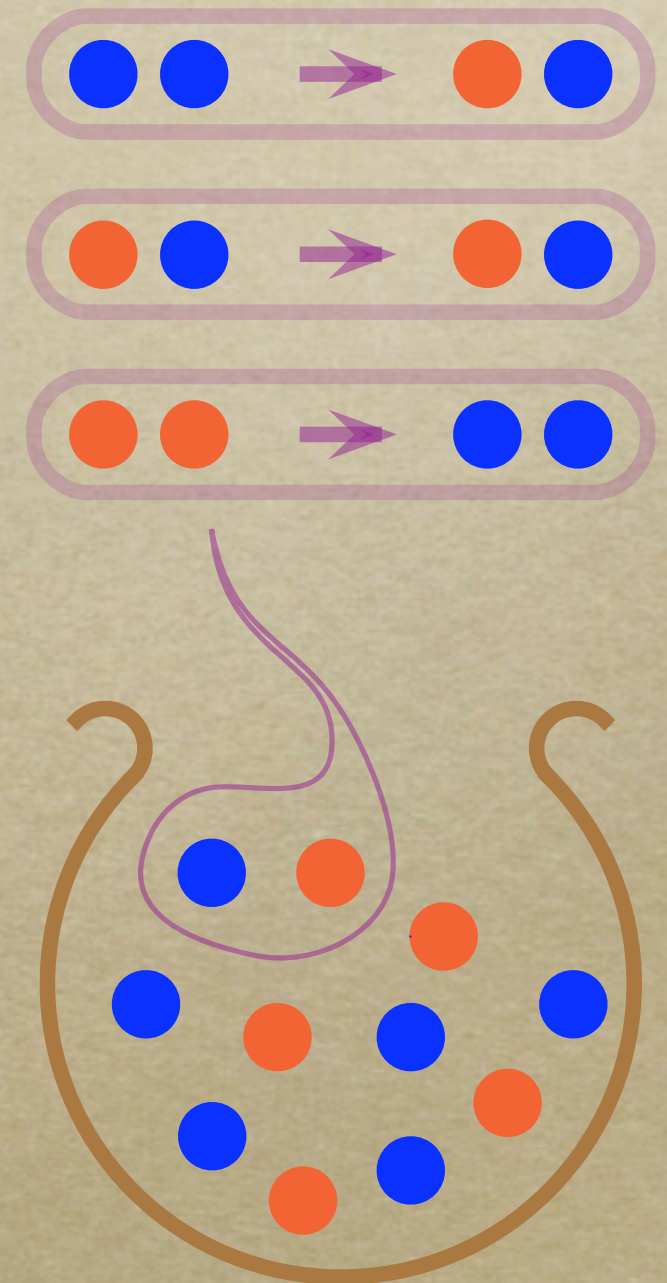


Population protocols : the general case



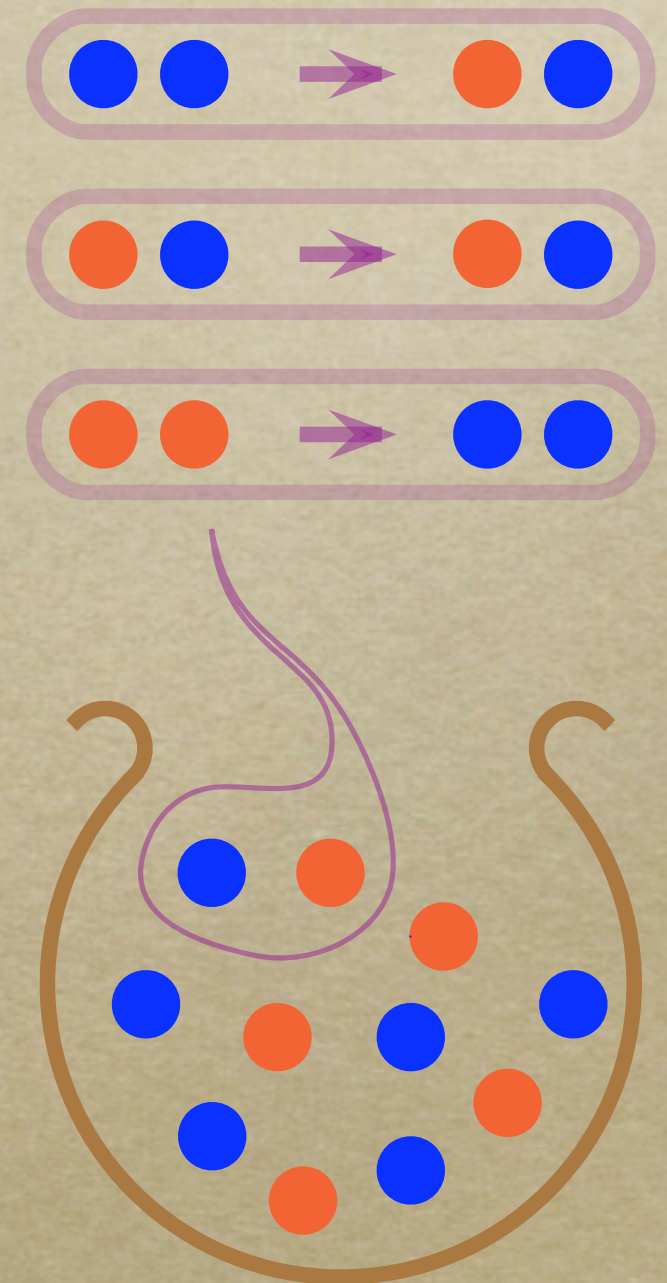
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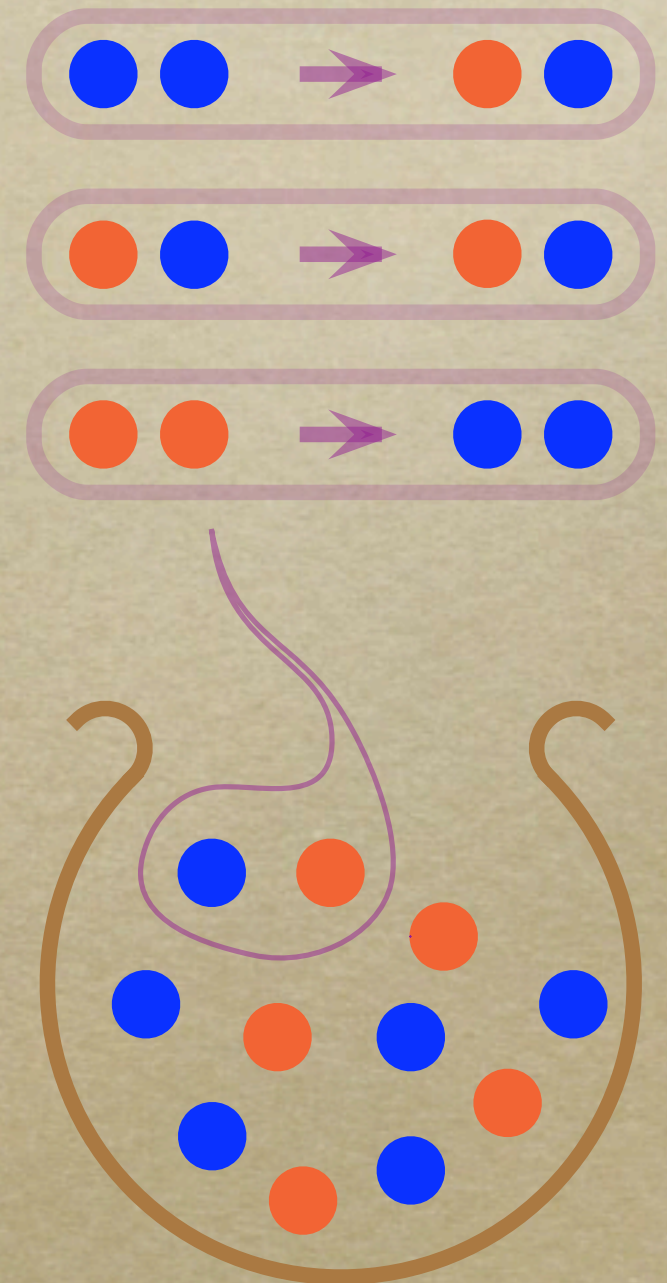
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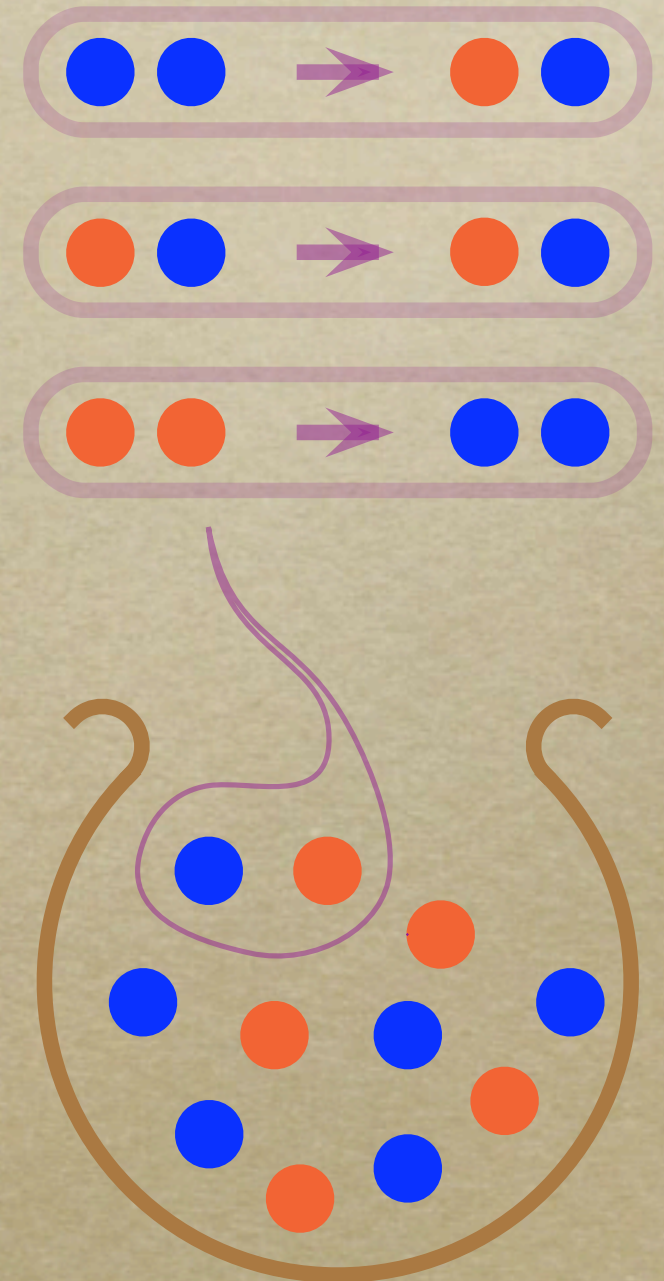


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- **Theorem** (Ph. Ch., Bournez et al.). Among the 26 possible rules, one is trivial, 10 converge to 0 or 1. For the 16 other rules, the stationary distribution of the proportion of *blue* balls is concentrated around p , when the number N of balls goes to ∞ . The error term is $O(N^{-1/2})$.



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